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LawnBott SpyderEVO LB1500 - Quick Start Guide

Main Components

1. Recharging Base (optional)
2. Battery Charger
3. Transmitter
4. LawnBott SpyderEVO LB1500
5. Perimeter Wire
6. Battery Charger Cables

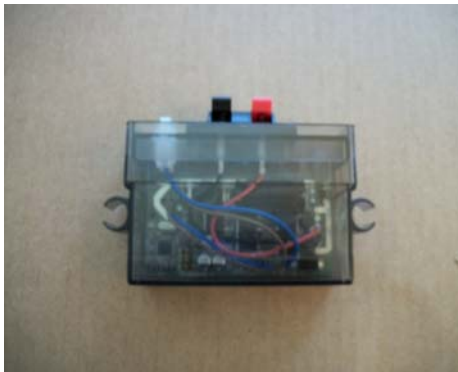
1.



2.



3.



4.



5.



6.



Installing the LB1500 without a Charging Base

1. Connect the Charger, Transmitter, and Battery Charger Cables together and place them in the area where you will be charging and storing the LawnBott. See Fig. 1



Fig. 1

Start your perimeter wire by stripping approximately $\frac{1}{4}$ in. on the end of the wire. Place it in the BLACK connector and run the wire out to the area where you will be running the LawnBott.

2. In a clockwise pattern, move around the perimeter of the yard, pegging the wire to the ground with the provided pegs.
3. When you come back to where you started the perimeter, use a peg to close the perimeter and run the wire back to the transmitter again, the wire may be twisted on its return if needed. See Fig. 2



Fig. 2

- 4. Once this is accomplished, strip approximately $\frac{1}{4}$ in. of wire from the other end and place it in the RED connector.**
- 5. Plug the Charger cable into the outlet and look at the transmitter for a blinking, red light that will confirm the wire has signal.**
- 6. It is now time to place the robot in the yard.**
- 7. Standing to the side of the robot, turn the robot on by pressing the “on/off” button and wait for confirmation that the unit is ready. The robot is ready when you hear the 2 “beep” audible sound.**
- 8. Standing to the side of the robot, press the “start/stop” button on the robot.**
- 9. The robot will go back and forth, then start the blade and begin to mow.**
- 10. At the end of the cutting time the robot will move towards the wire and stop on top of the perimeter wire to indicate it is time for the robot to recharge.**

LB1500 with Charging Base

1. The charging base has a space to place the charger on the side of the arch with the white plug.
2. Connect the small, blue and brown connector to the designated spot on the transmitter.
3. Place the transmitter into the sidewall of the Charging Base with the RED and BLACK connectors facing DOWN. See Fig. 3



Fig. 3

4. Place the Charging Base in an area of the yard, where the white charging base connector reaches the charger and outlet without tension.
5. It is important that the Charging Base be placed in an area that has a straight line, minimal of 10 to 12ft. to give the robot a straight line when following the wire. Please refer to the diagram below (Fig. 4) for wiring references.

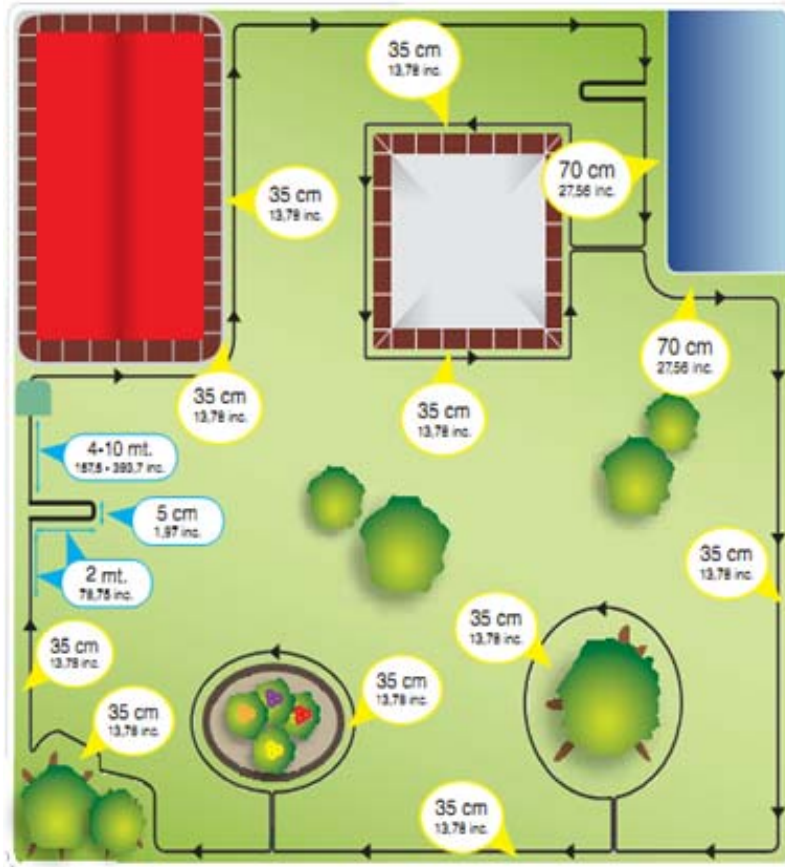


Fig. 4

6. Please be sure to include the “antennae gate” that comes before the charging base. It is critical for the robot to be able to dock.
7. Once you have completed the wire installation you wire ends should be plugged in, in the following way:

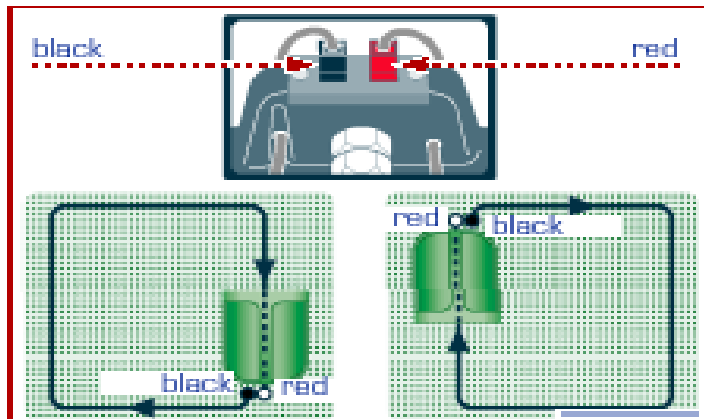


Fig. 5

8. The transmitter should blink a series of RED lights to indicate that there is signal being transmitted.